

Operational Procedures using *THALES Avionics* HUD/EVS “ENHANCED VISION SYSTEM”

A report on an experiment
with the BOEING 737- 300 simulator



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SUMMARY

■ STATUS

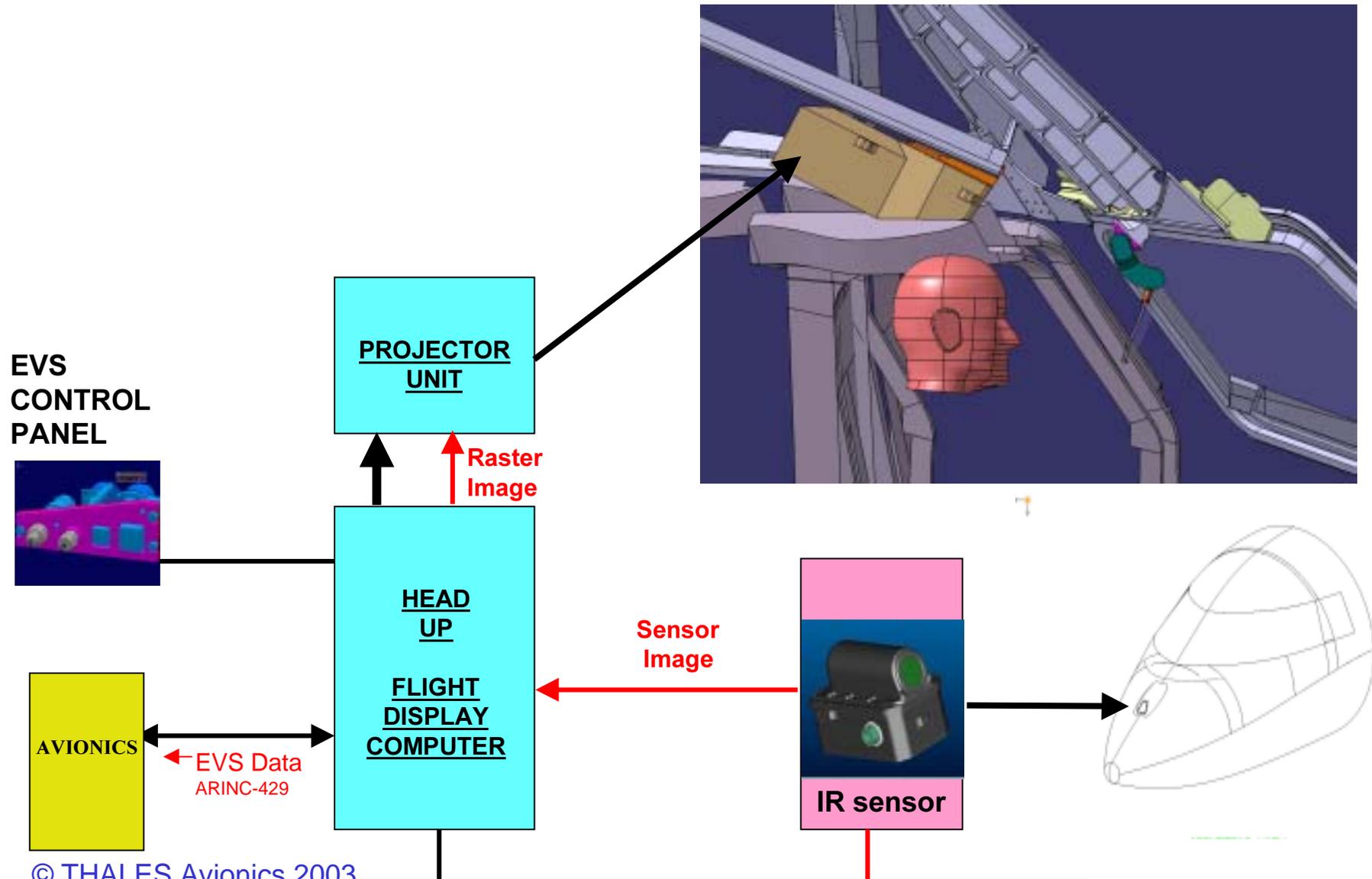
- Since 1992 with NORTHWEST Airlines

■ CONTENT OF « SIGNAL 2 » STUDIES

■ RESULTS OF THE EXPERIMENT :

- CAT I EVS
- NPA EVS

■ CONCLUSION - NEXT STEP FORWARD



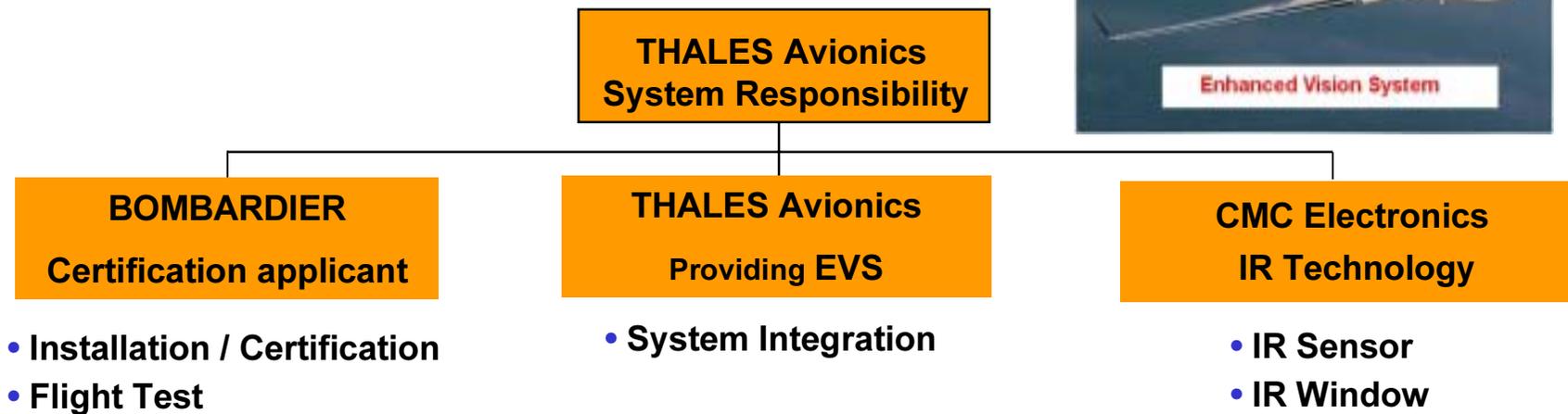
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HFDS + FLIR EVS

- Basic on **GEX** and Option for **GLOBAL 5000**
- Certification (TC) : 1st Q 2005

GLOBAL EXPRESS



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- Gulfstream G-V EVS Special Condition (FAA/STC) - **06/2001**
 - FAA Statements
 - Enhancement of pilot's situational awareness
 - EVS image compensates the field of view obstruction due to raster display (safely and in compliance with §25.773).

- FAA Notice for Proposal RuleMaking (NPRM) in progress for Enhanced Flight Vision System (EFVS)- **Initialized in 02/2003**
 - Objective : Takeoff and landing under IFR (§91.175) Amdt
 - EFVS enables the pilot to determine « enhanced flight visibility » at MDA(H) or DA(H) in lieu of flight visibility [cf. §91.175(c)(2)] ;
 - EFVS permits descent and operation below MDA(H) or DA(H) based on EFVS images

Note : NPRM doesn't cover CAT II and CAT III operations

Authorities involved :

- **CAA / DPAC (CONTRACT MANAGER)**
- **CAA / DGAC / OCV**
- **CAA / DGAC / SFACT / E (OPERATIONS)**
- **DGA / CEV (FLIGHT TEST CENTER)**

Airlines (pilot panel) :

- **AIR France (through SNPL COMETEC)**
- **BRIT AIR**

...and Aircraft Manufacturers :

- **BOMBARDIER**
- **DASSAULT AVIATION (FALCON F7X)**
- **AIRBUS**



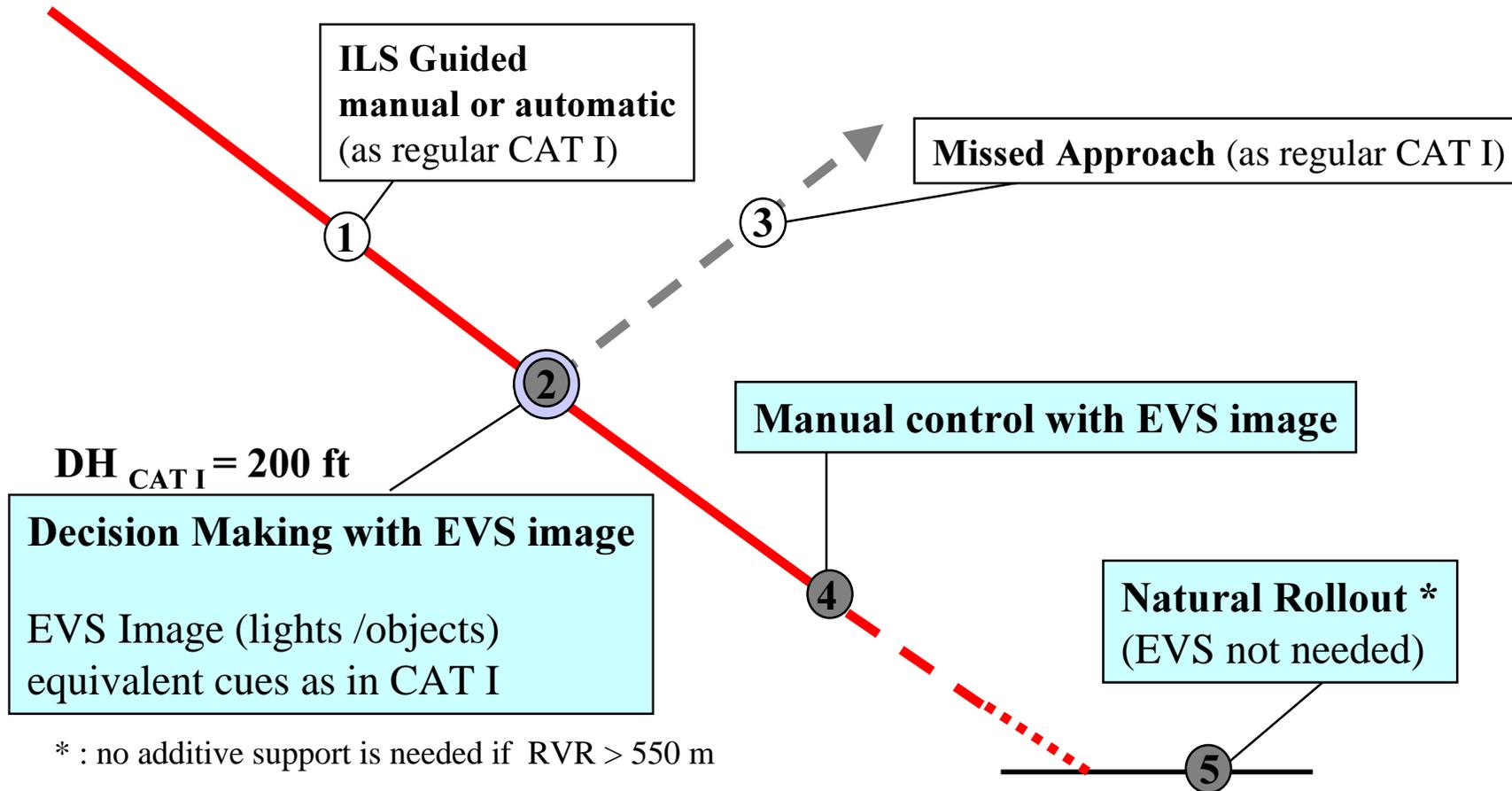
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Cat I precision approach with EVS

JAR OPS 1.430 and AC 120-29A appendix 7 (C074)

Cat I minima (with lateral and vertical guidance)				
Decision height	Facilities/RVR			
	Full	Interm	Basic	Nil
(JAR) 200ft	550 m	700 m	800 m	1000 m
(FAR) 200ft	550 m	750 m	1000 m	1200 m

RVR reduced to 550m 1800ft



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JAA precision approach CAT I RVR minima



	FULL	INTER	BASIC	NIL
DH	RVR for Category C Aircraft (B 737-300)			
200 ft	550 m	700 m	800 m	<u>1000 m</u>
201-250 ft	600 m	700 m	800 m	1000 m
251-300 ft	650 m	800 m	900 m	1200 m
301 ft +	800 m	900 m	1000 m	1200 m

Airport Database Simulator THAV Constraint

ICAO CODE LFBD

Non conformity(1) :
for - contrast and brightness of lights
- geometry of ALS

Non conformity(1)
of Airport ALS Simulator THAV Constraint

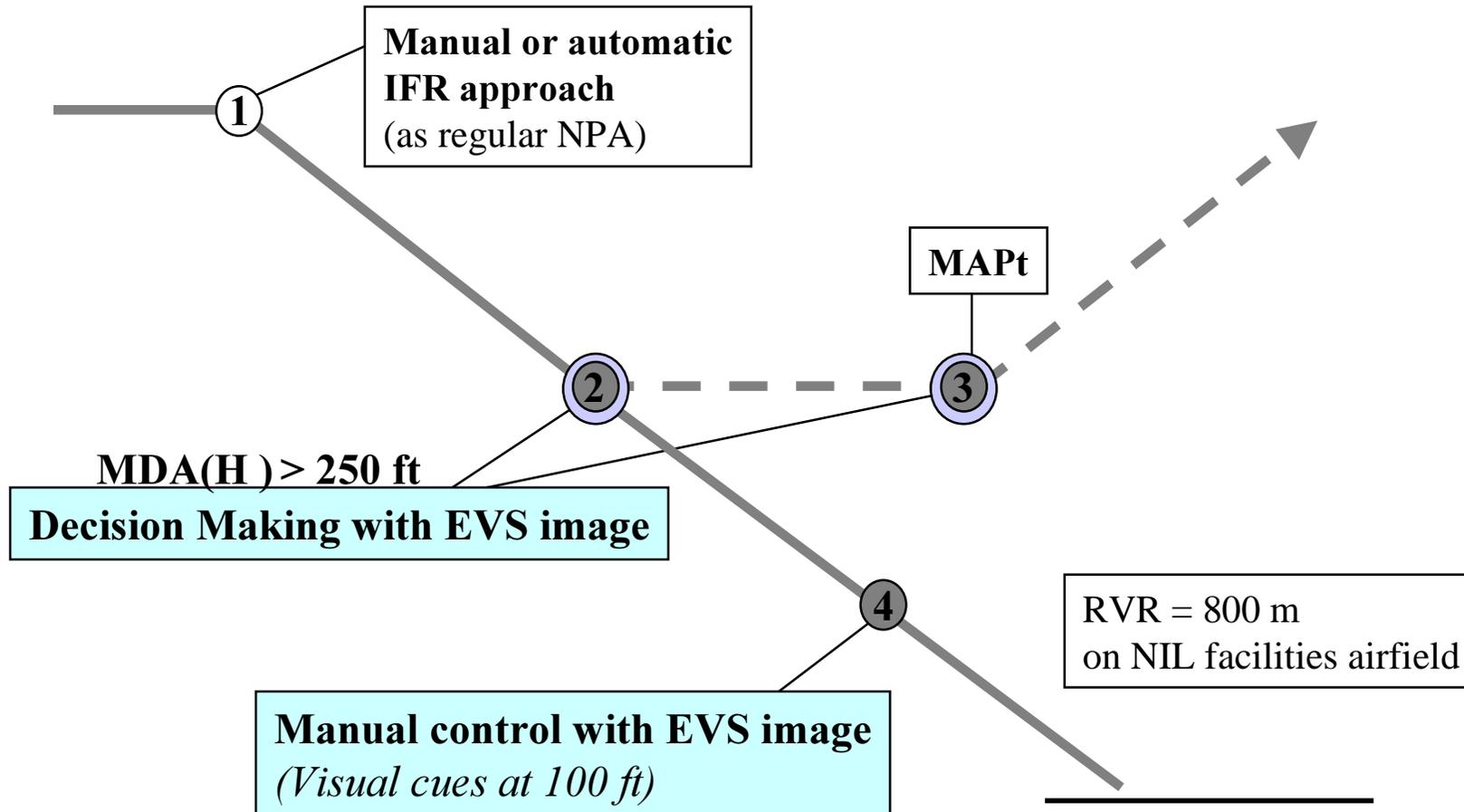
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Non Precision Approach with EVS

JAR OPS 1.430 and AC 120-29A appendix 7 (C053 and C054)

Straight-In minima (NPA)				
MDA (H)	Facilities/RVR			
	Full	Interm	Basic	Nil
250 ft to	800 m	1000 m	1200 m	1500 m
>650 ft	1800 m	2000 m	2000 m	2000 m

RVR reduced to 800m 2400ft



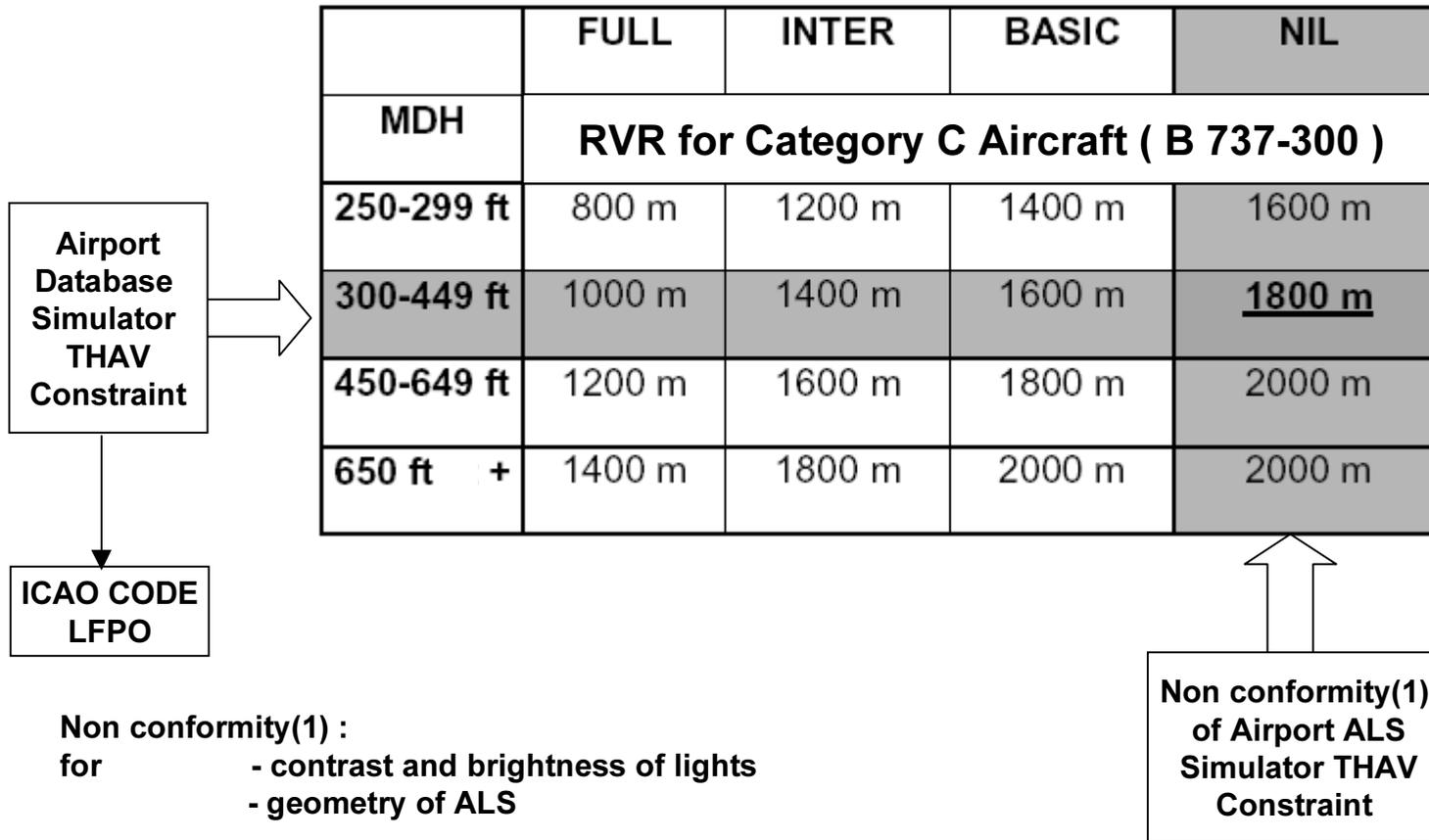
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JAA Non Precision Approach RVR minima



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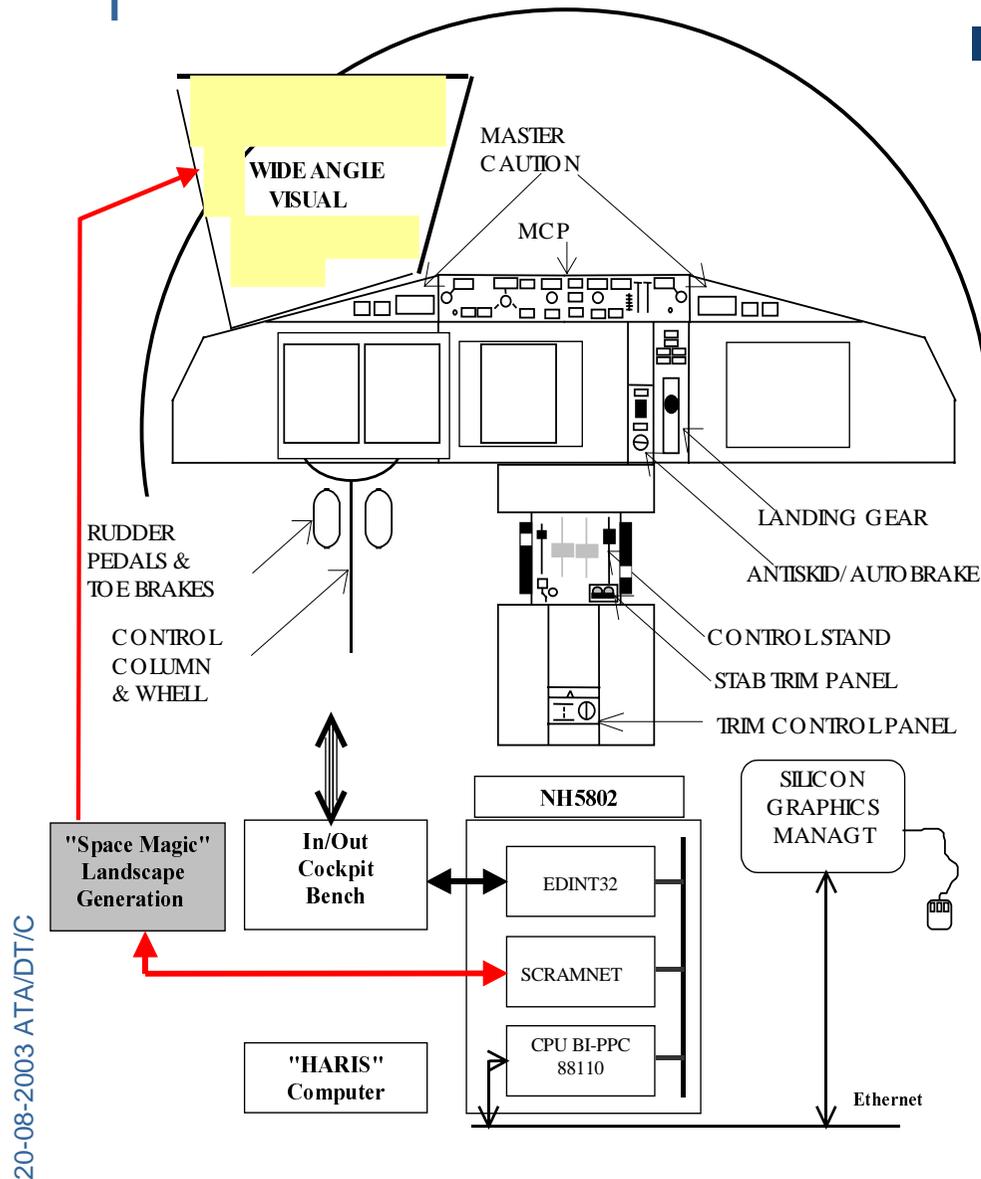
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Baseline without HUD

- STANDARD CONFIGURATION
 - NO HUD
 - USED FOR INITIAL TRAINING
 - USED TO GENERATE THE « BASELINE »
 - MEASUREMENT OF THE PILOT'S STANDARD PERFORMANCE (reference)



Simulation Image - good weather conditions



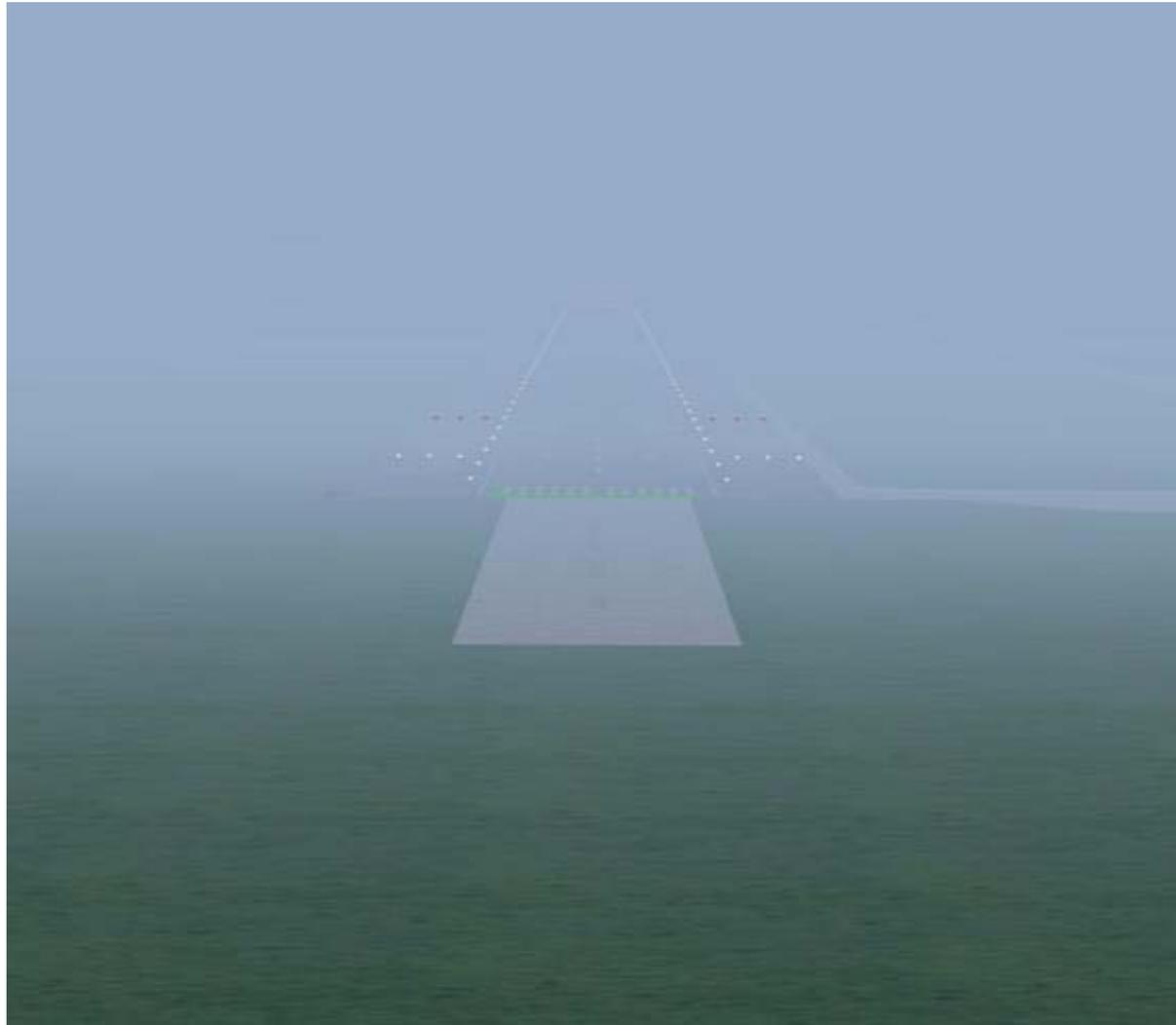
Setting of VISUAL for initial training : CAVOK - Height = 200 ft

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Setting of VISUAL in « BASELINE ILS CAT I »
ALS OUT - RVR = 1000 m - Height = 200 ft

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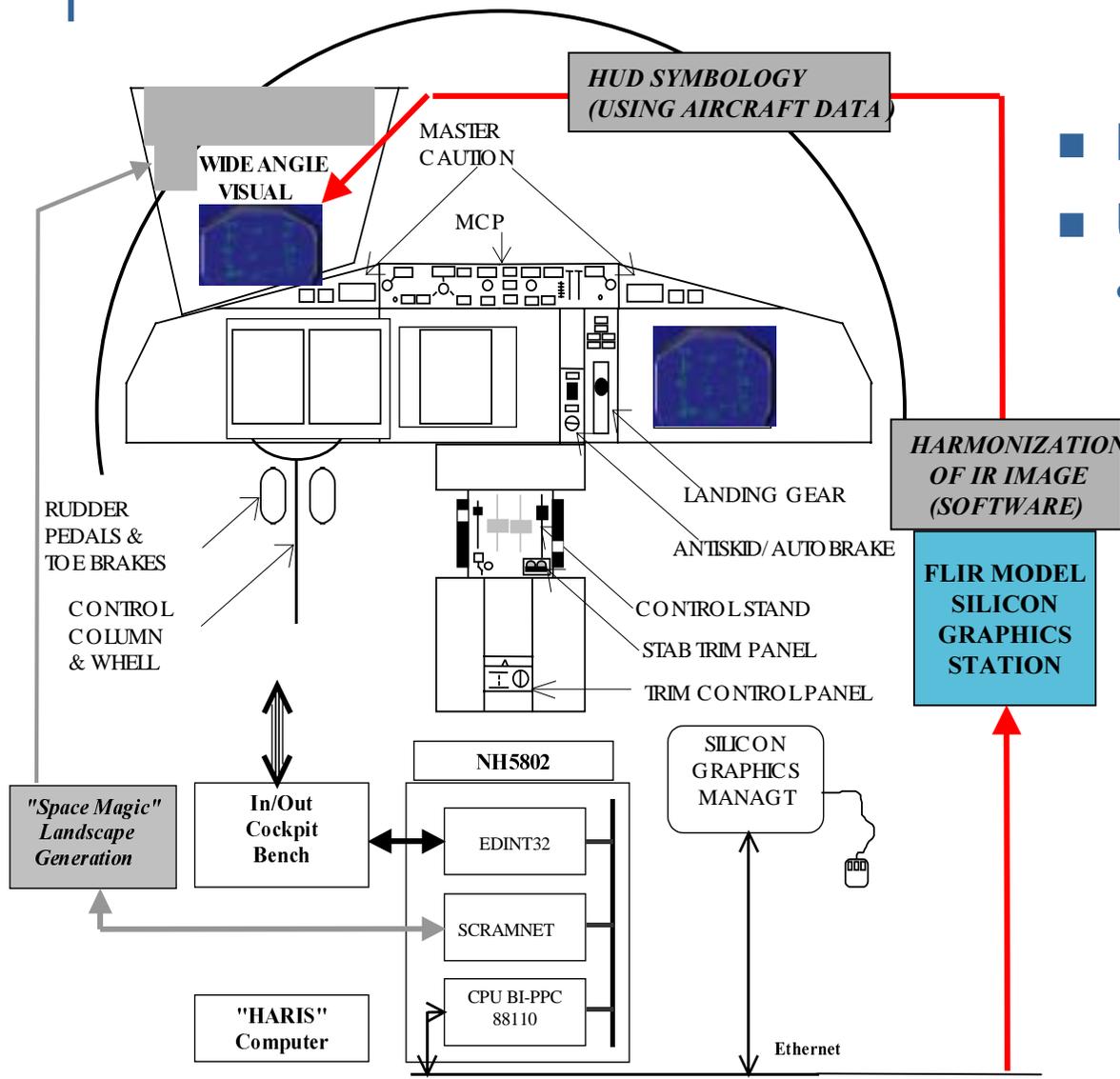
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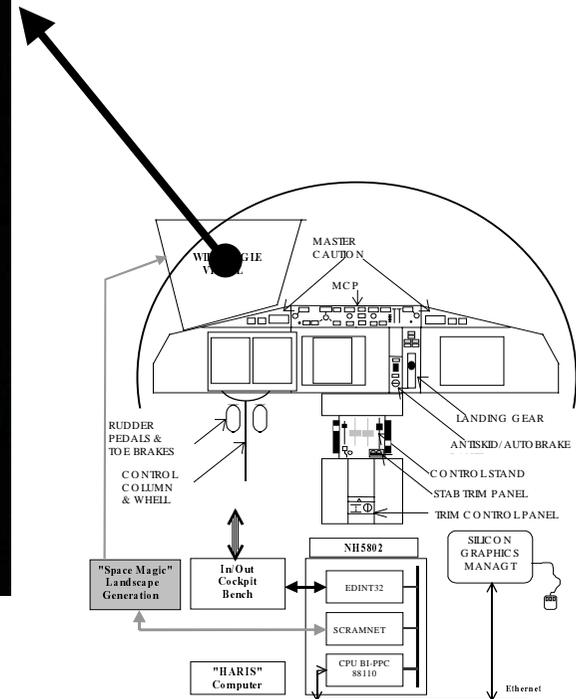
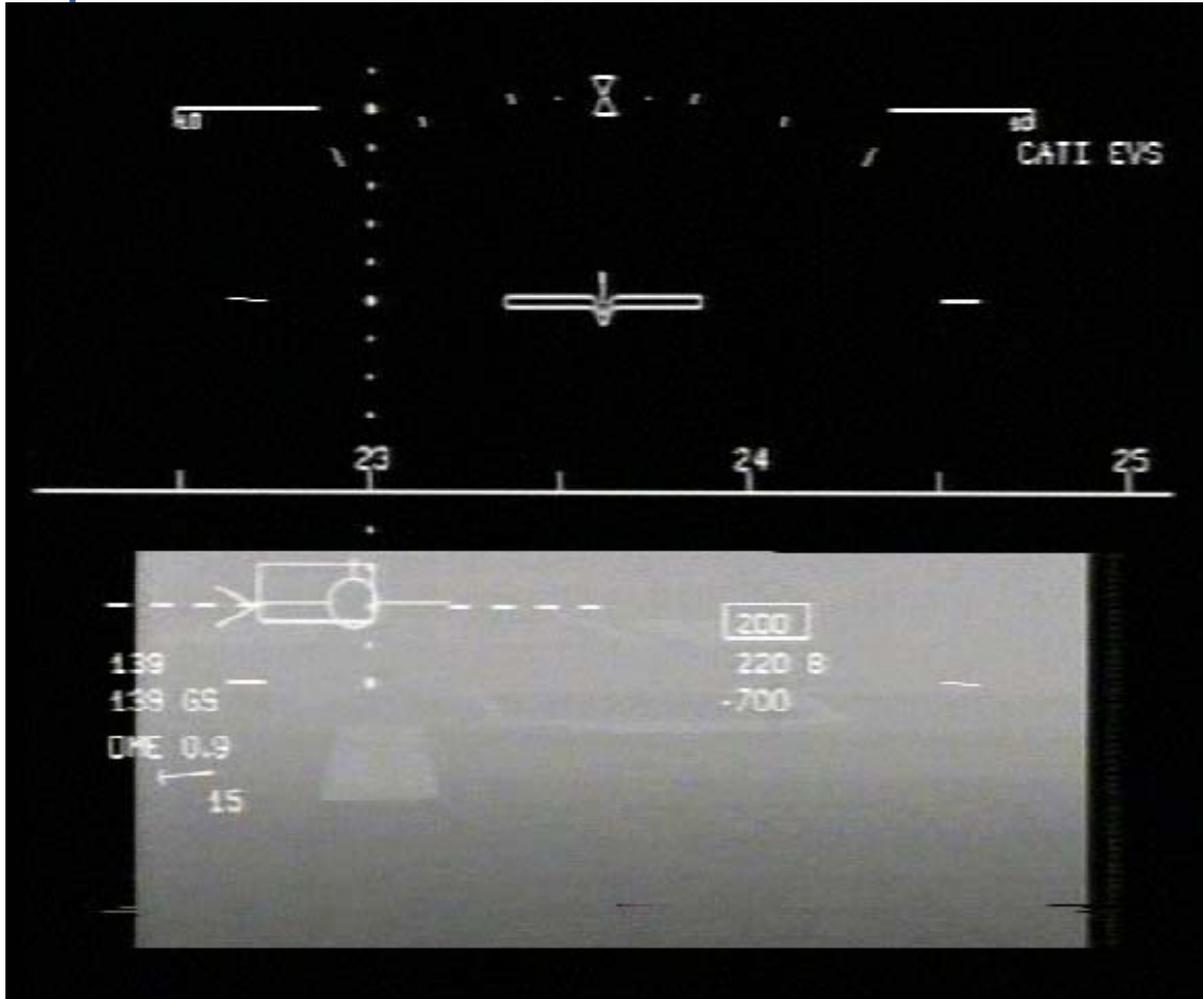
HUD/EVS Configuration

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- HUD WITH EVS IMAGE (1)
- USED TO :
 - MEASUREMENT OF THE PILOT'S PERFORMANCE

Example of Cat I EVS Image



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- The runway threshold in IR imagery appears 3 seconds before Decision Height.
- Airfields selected : « ALS OUT » configuration.

HUD/EVS is a combined use of HUD symbology and IR image.

Simulated Aircraft configuration



- B737-300
- GROSS WEIGHT : 40 tons
- FLAPS SETTING
 - RUN START : 0°
 - LANDING : 30°
- SPEED
 - RUN START : 240 kt
 - LOC INTERCEPT : 210 kt
 - FINAL APP : 140 kt

- 2 experts (CAA/DGAC/OCV) for validation of EVS procedures
- 7 Air Transport pilots flying in airlines
 - HUD trained and non trained
 - B737 qualified and non qualified

PE1	PE2
Aged 58	Aged 53
15762 h	15400 h
Captain	Captain
B747	B747

PL1	PL2	PL3	PL4	PL5	PL6(*)	PL7
Aged 52	Aged 53	Aged 32	Aged 30	Aged 52	Aged 36	Aged 51
14500 h	13000 h	2400 h	3000 h	11000 h	5500 h	8000 h
Captain	Captain	F.Off	F.Off	Captain	Captain	Captain
CRJ100	CRJ100	B777	A320	B747	B737	B777

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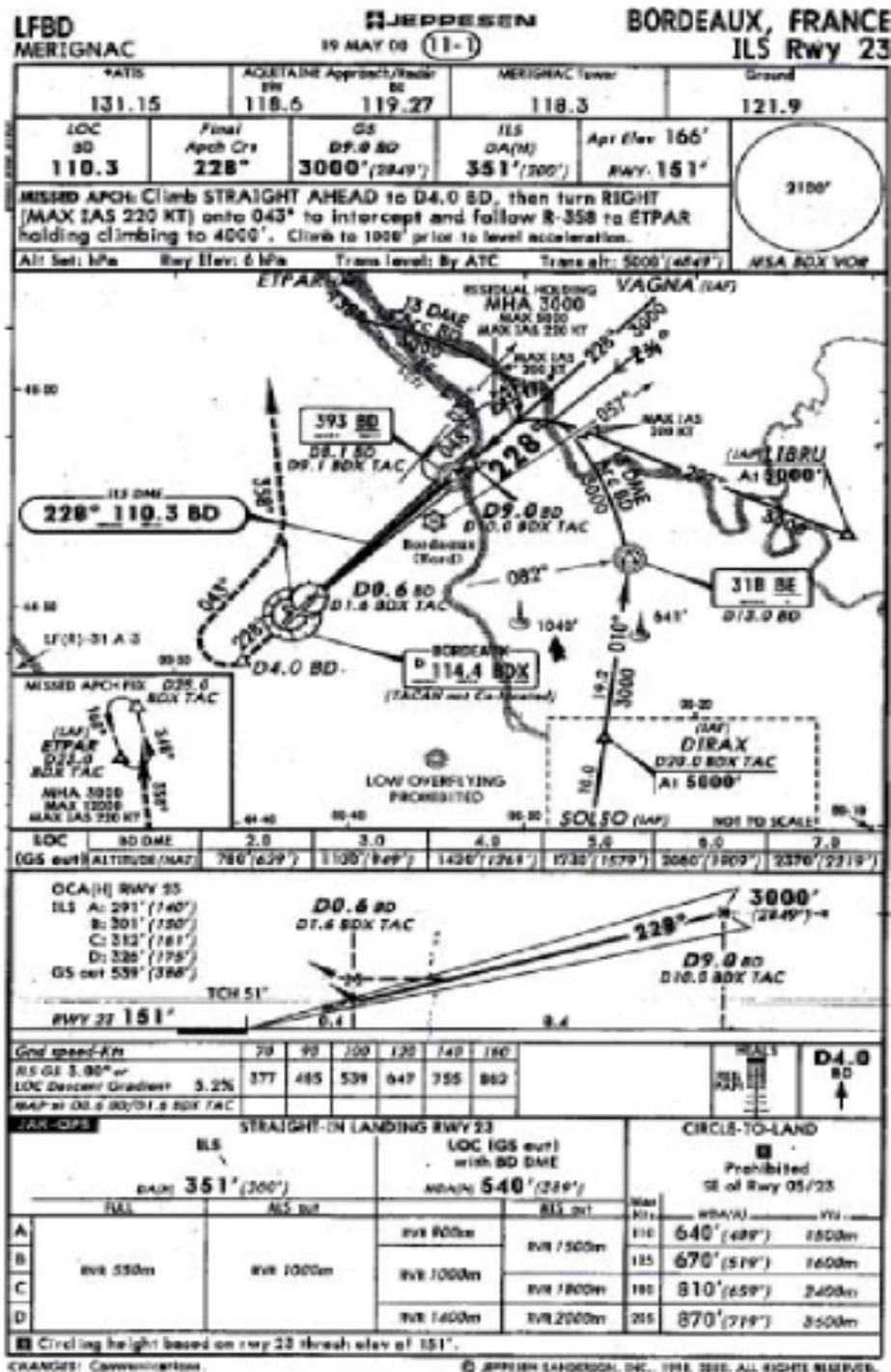
List of discrete criteria used for pilot performance measurement

- TOTAL NUMBER OF :
 - SUCCESSFUL LANDINGS
 - GO-AROUND
 - TOUCHDOWN THEN GO-AROUND
 - CRASHES

- TOTAL NUMBER OF CASES WHERE MAIN WHEELS:
 - ARE UNDER FLIGHT PATH ANGLE (3°)
 - ARE UNDER THE OBSTACLE CLEARANCE

List of continuous criteria used for pilot performance measurement

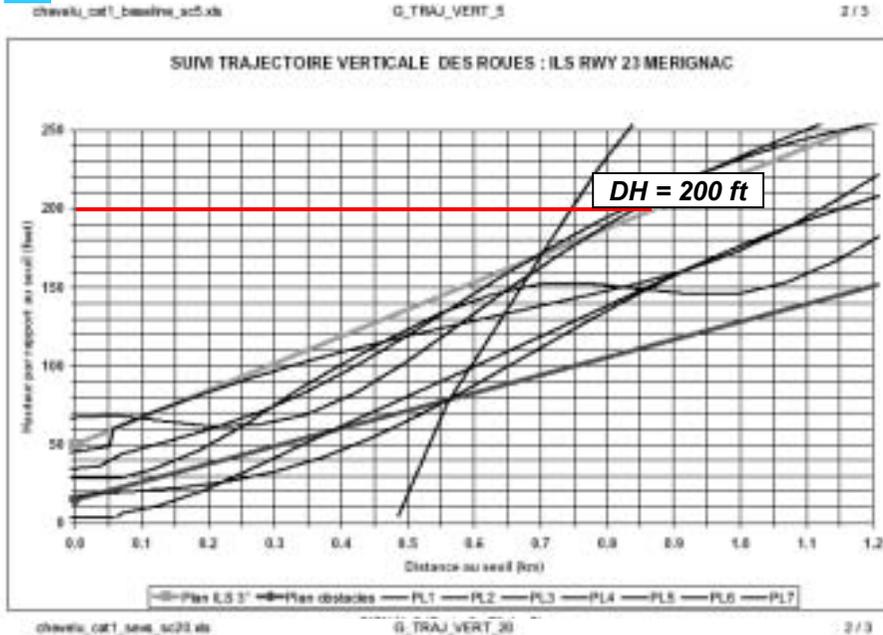
- « *Flight Crew Licensing* » regulations
 - HEIGHT at DH or MDH (+50 ft tolerance)
 - HEIGHT at TCH (Threshold Crossing Height - Z =50 ft)
 - HEADING VALUES (+ or - 5°)
 - HORIZONTAL SPEED (+ or - 5 kt)
- « *All Weather Operations* » regulations
 - LONGITUDINAL TOUCHDOWN DISTANCE (threshold)
 - LATERAL TOUCHDOWN DISTANCE
- « *Aircraft limitations* »
 - VERTICAL SPEED (Landing gear limitations)
 - ROLL VALUES (+ or - 8° due to B737 nacelle position)



Experiment 1 Scenario

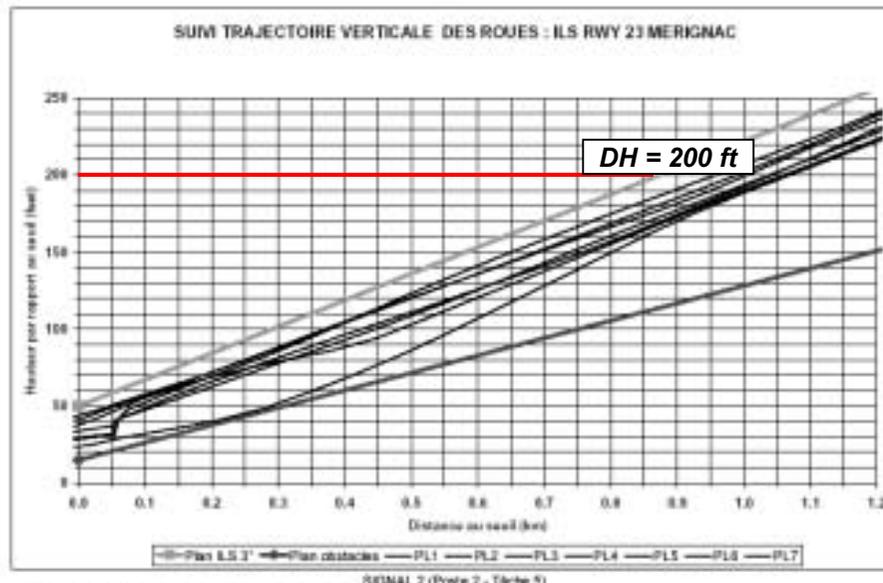
- ILS CAT I Rwy 23
- JAR OPS
- BORDEAUX, France
- BRIEFING STRIP 11-1 JEPPESEN
- Axis : 228°
- ILS Glide slope 3° or 5,2%
- DH = 200 FT at 0,4 Nm of runway threshold
- For « Category C » A/C
 - ALS OUT : RVR = 1000m 3000ft
 - ALS FULL : RVR = 550m 1800ft
- IAF « LIBRU » 5000' (~9 min)
- Wind : 320° 15 kts

CAT I + EVS 250 ft - 50 ft Segment



WITHOUT HUD/EVS

- N=7 Standard ILS CAT I App
- RVR = 1000 m - FOG
- ALS out

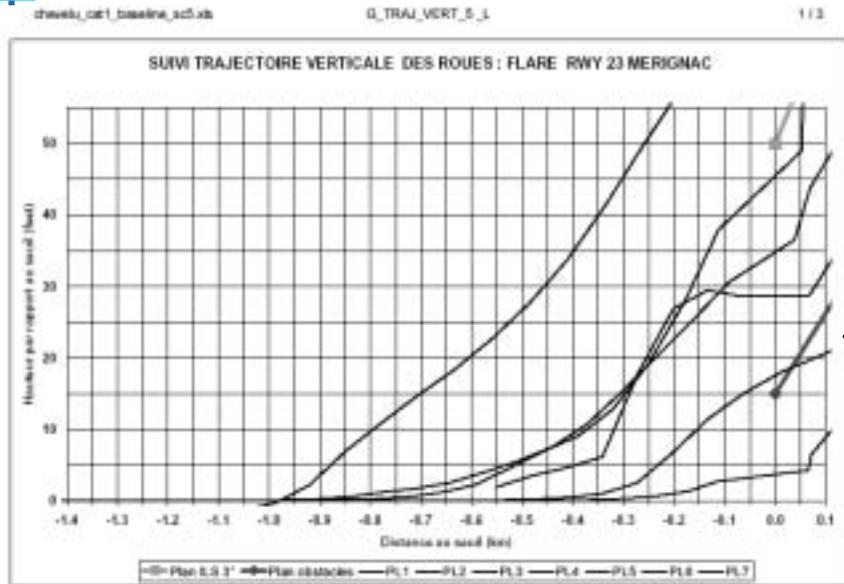


WITH HUD/EVS 😊

- N=7 ILS CATI EVS App
- RVR reduced to 550 m - FOG
- ALS out and DH = 200 ft
- Results :
 - Stability of flight
 - FCL tolerances improved

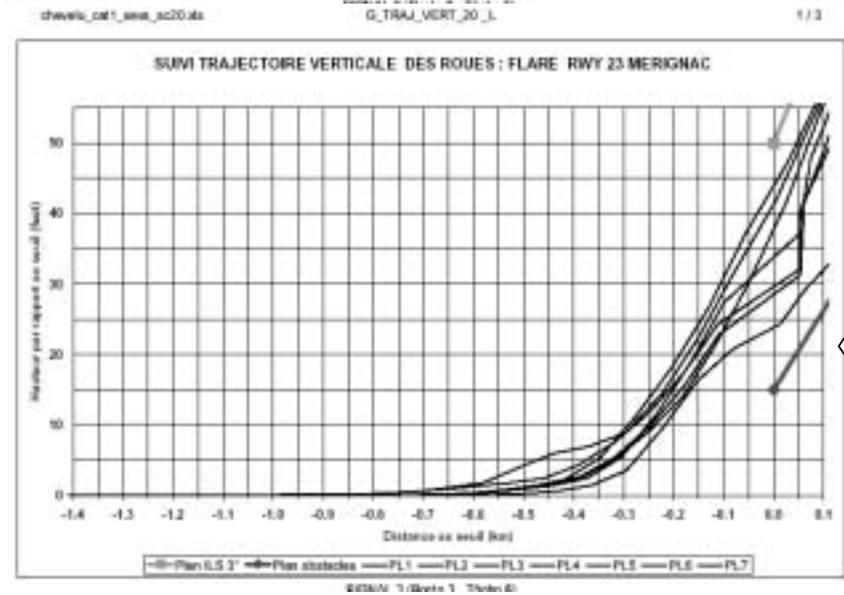
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CAT I + EVS 50 ft - 0 ft Segment



WITHOUT HUD/EVS

- Standard ILS CAT I
 - RVR = 1000 m - FOG
 - No Runway Center Line
 - Success rate : 5/7 LANDINGS
- (71%)



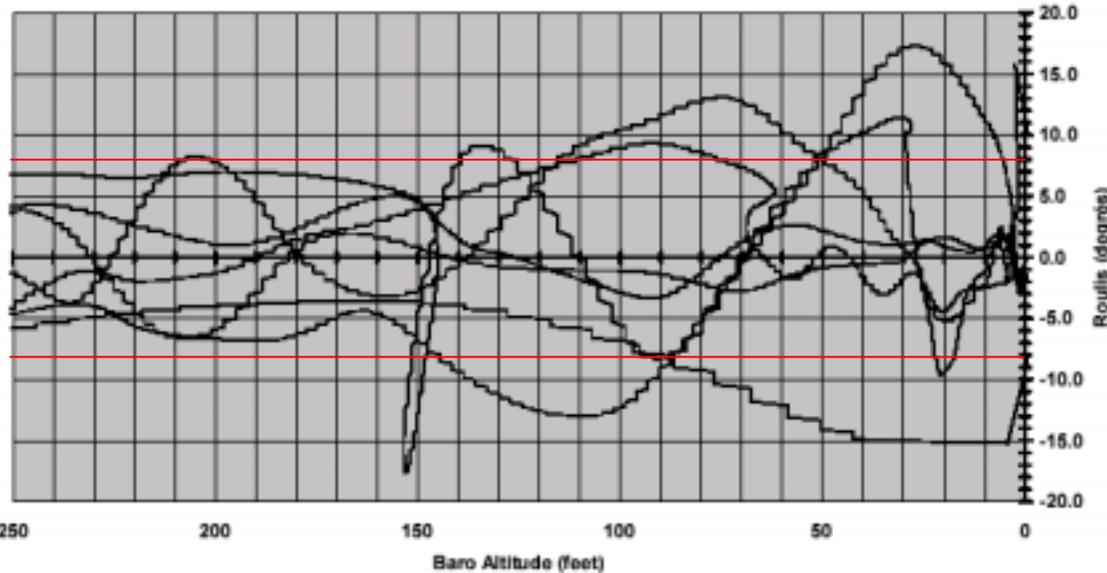
WITH HUD/EVS

- ILS CAT I EVS
 - RVR = 550 m - FOG
 - No Runway Center Line
 - Success rate : 7/7 LANDINGS
- (100%)

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Cat I + EVS Aircraft Attitude Control

Chevelu "Scénario 5"

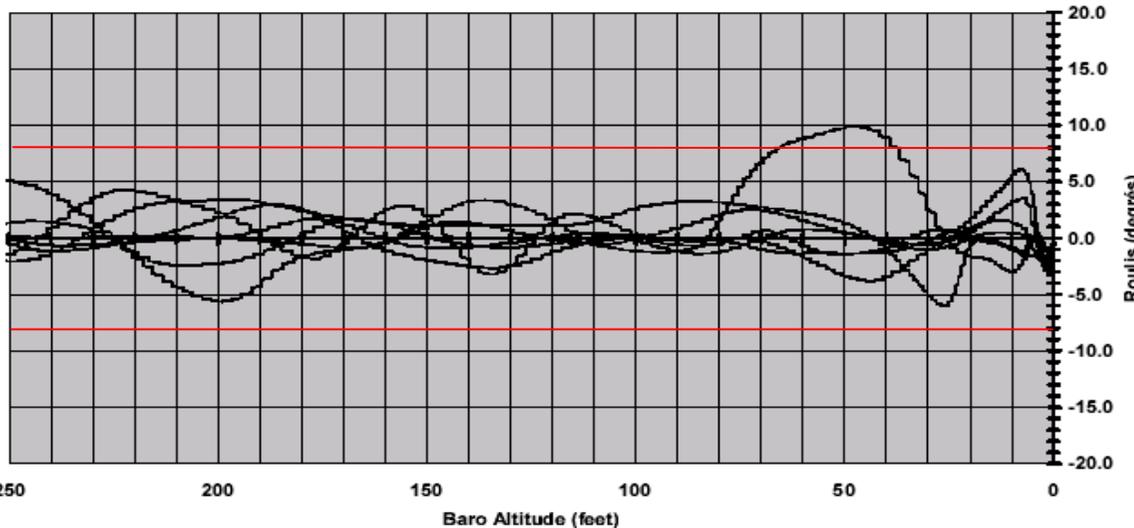


ROLL 250 ft - 0 ft

WITHOUT HUD/EVS

- Standard ILS CAT I
- RVR = 1000 m - FOG
- ALS out

(Max variation + 17° - 18°)



WITH HUD/EVS ROLL CONTROL IMPROVED

- ILS CAT I EVS
- RVR = 550 m - FOG
- ALS out

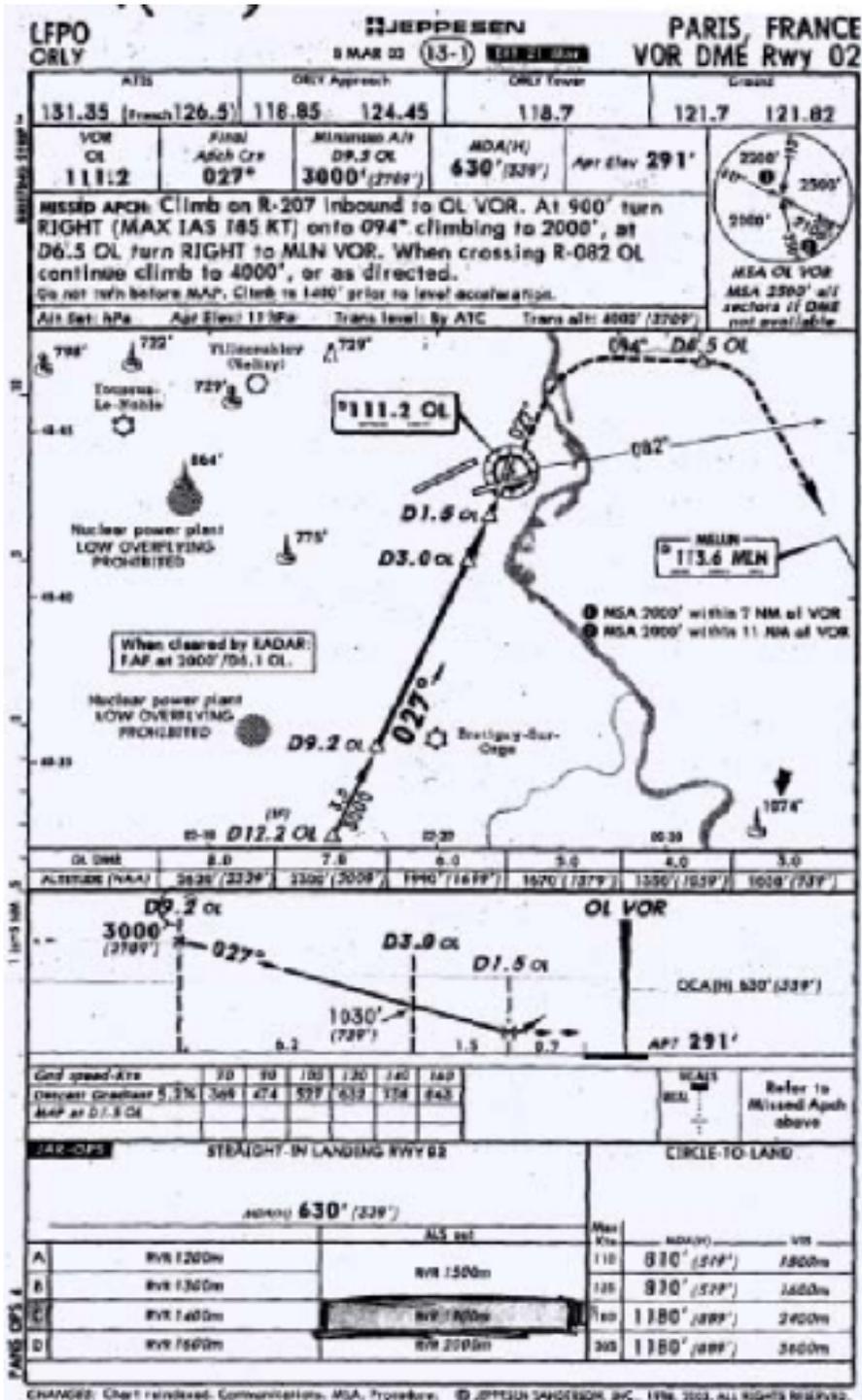
(Max variation + 10 - 6°)

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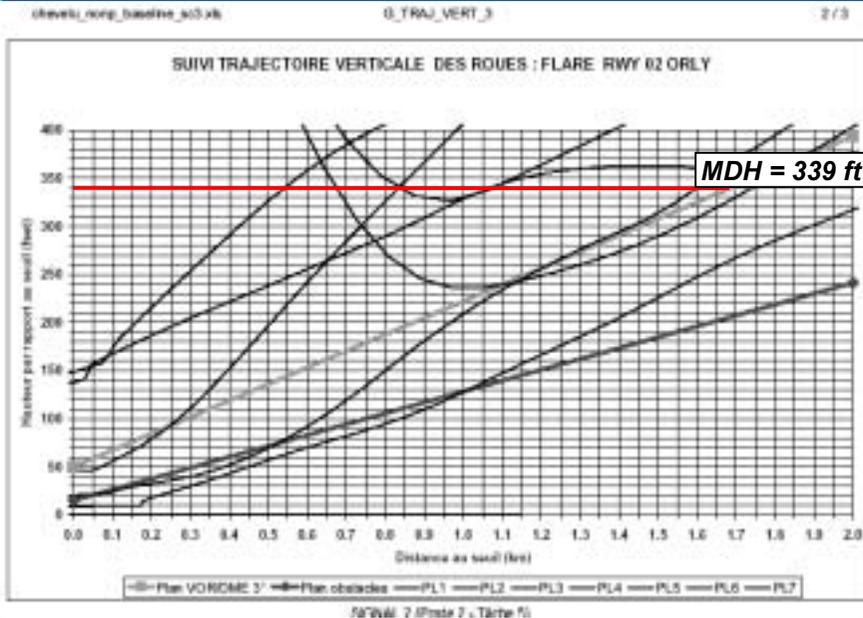
Experiment 2 Scenario

- VOR DME Rwy 02
- JAR OPS
- PARIS, France
- BRIEFING STRIP 13-1 JEPPESEN
- AXIS 027° (offset 7°)
- Descent Gradient 5.2%
- MDH = 339 ft at 0.7 Nm of runway threshold
- For « Category C » A/C
- ALS OUT : RVR = 1800m 600ft
- ALS FULL : RVR = 1400m 450ft
- IAF « ODRAN » 39 Nm in SW of OL VOR (~12 min)
- Wind : 320° 15 kts

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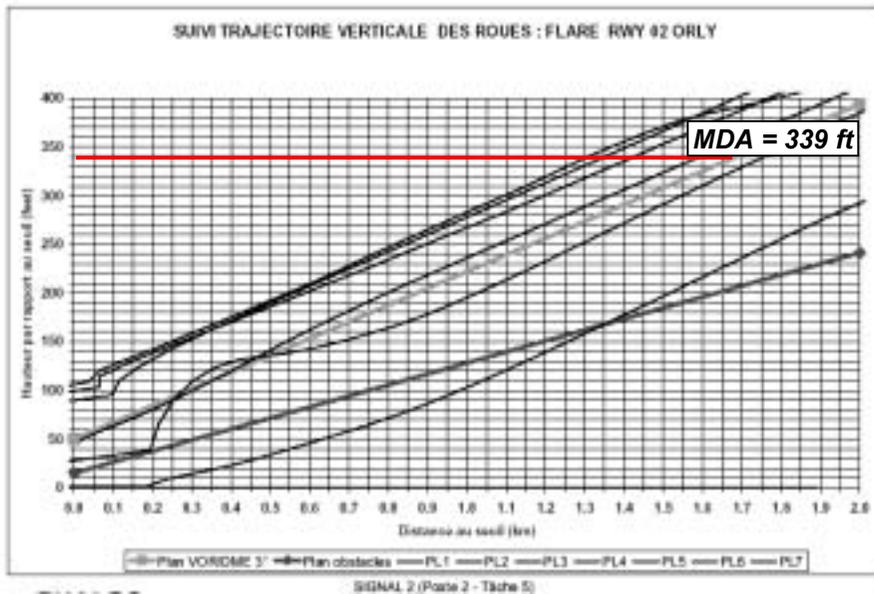


NPA + EVS 400 ft - 50 ft Segment



WITHOUT HUD/EVS

- Standard VORDME
- RVR = 1800 m - FOG
- ALS out
- 2 GO-AROUND

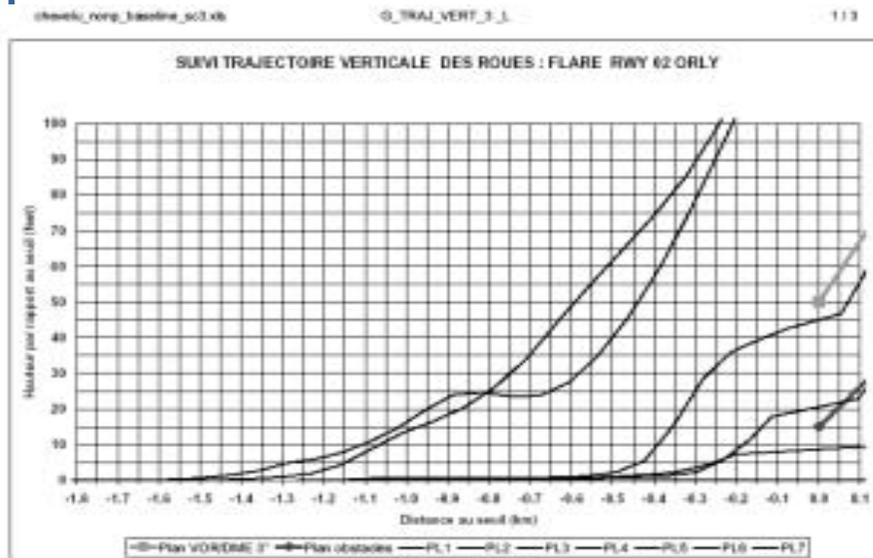


WITH HUD/EVS

- VOR DME EVS
- RVR = 800 m - FOG
- ALS out and MDH 339 ft
- Results :
 - Stability of flight
 - FCL tolerances improved

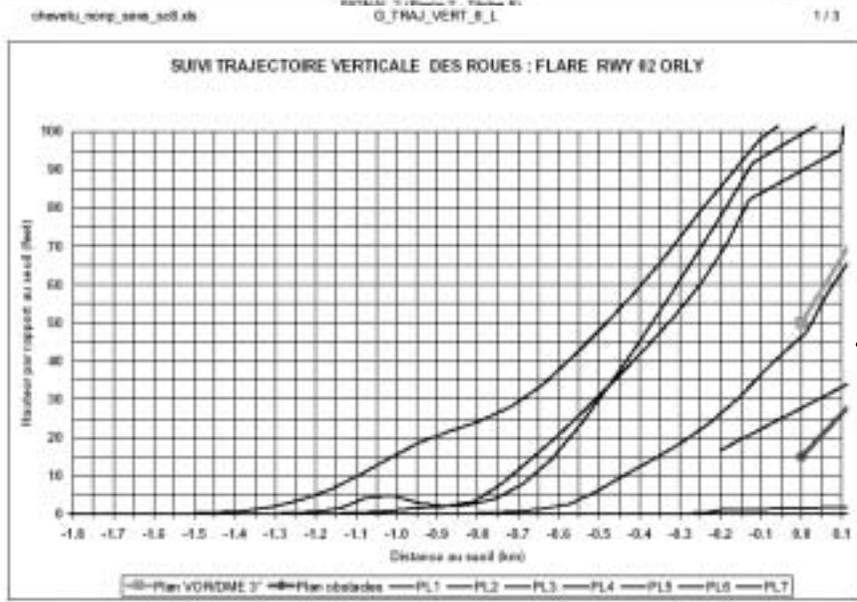
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NPA + EVS 50 ft - 0 ft Segment



WITHOUT HUD/EVS

- Standard VORDME
 - RVR = 1800 m - FOG
 - No Runway centerline
 - Success rate: 5/7 LANDINGS
- (71%)



WITH HUD/EVS ☺

- VOR DME EVS
 - RVR = 800 m - FOG
 - No Runway Center Line
 - Success rate : 5/6 LANDINGS
- (83%)

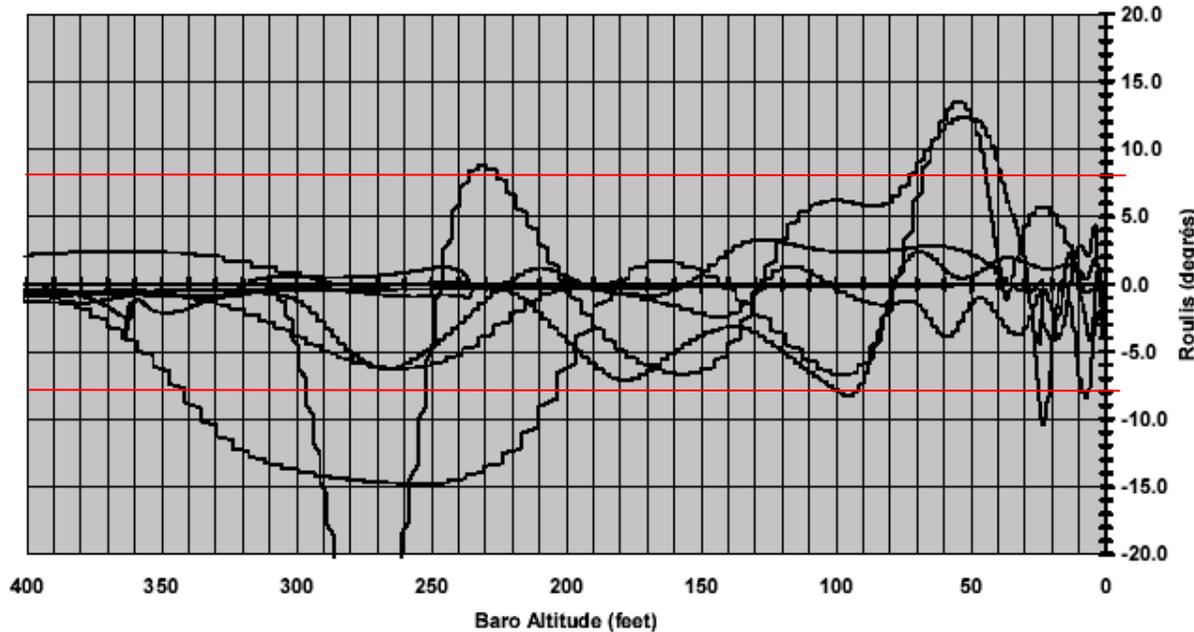
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NPA + EVS Aircraft Attitude Control

ROLL 400 ft- 0 ft

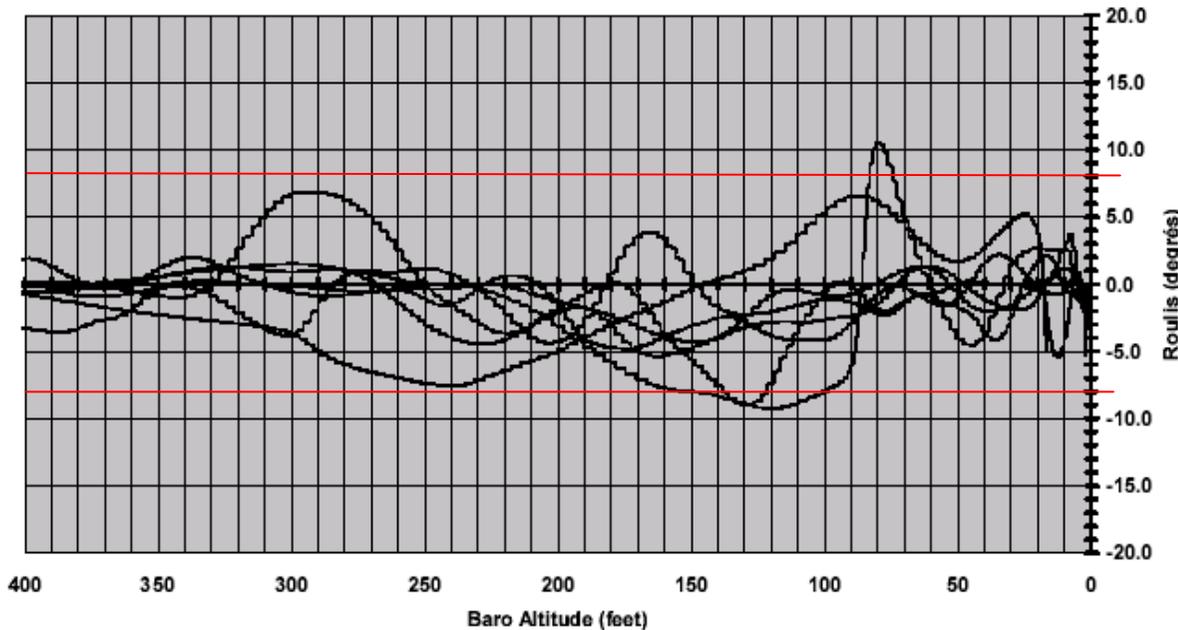
WITHOUT HUD/EVS

- Standard VORDME
- RVR = 1800 m - FOG
- ALS out



WITH HUD/EVS 
ROLL CONTROL
IMPROVED

- VOR DME EVS
- RVR = 800 m - FOG
- ALS out



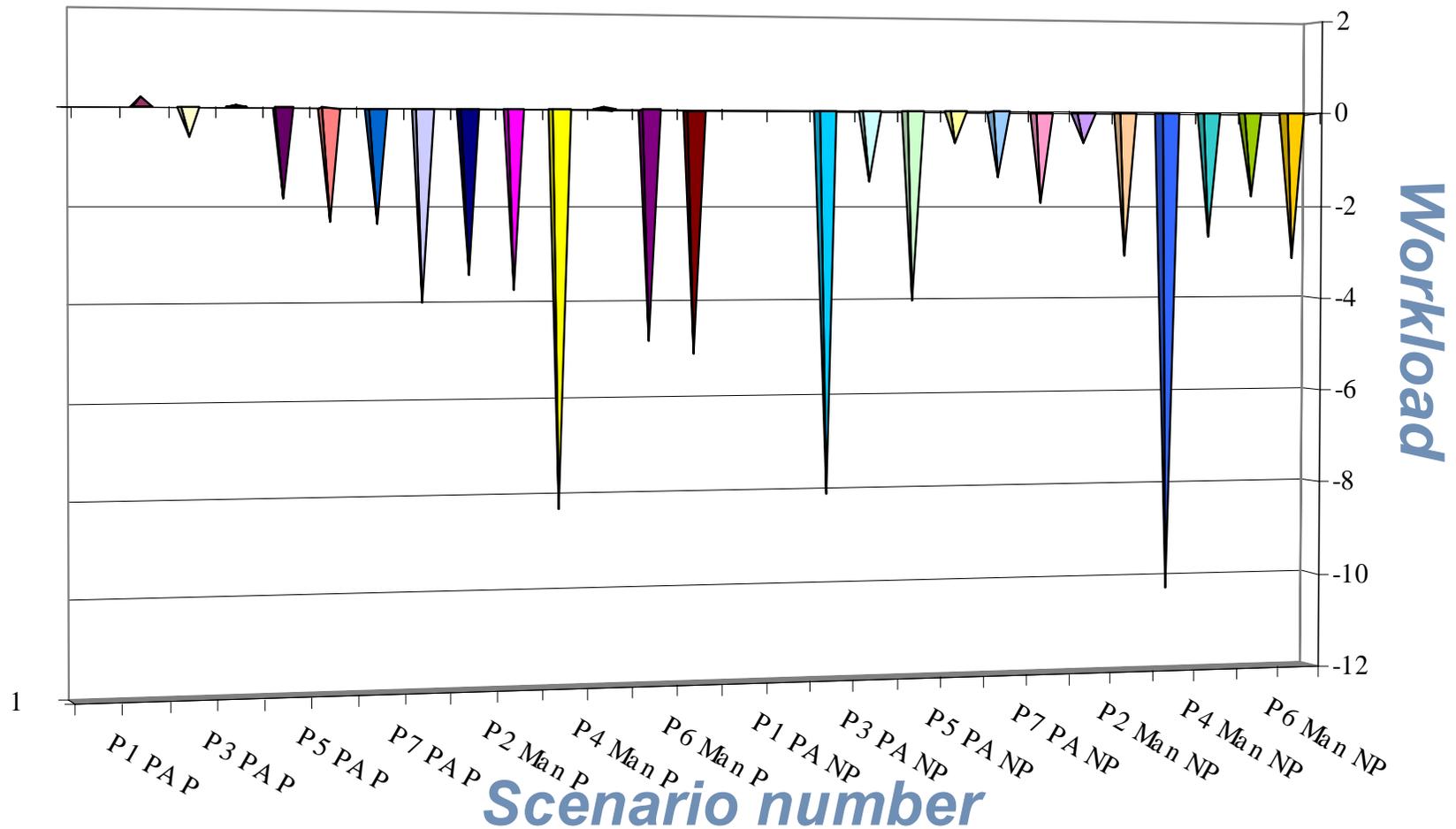
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Workload analysis

- Experimental method
 - After training and familiarization, the pilots perform the baseline scenarios then HUD/EVS scenarios
- Workload :
 - analysed using “NASA-Task Load Index” method
- Results :
 - The confidence intervals test is significant (threshold 0,01) and shows a workload decrease when HUD/EVS is used.

Workload during Normal Conditions

EVS vs Baseline workload decrease (NASA-TLX)



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- Has developed a concept to get an “*Additional credit use*” HUD/EVS
- Has demonstrated :
 - Enhanced Approach procedures (ILS CAT I EVS / VORDME EVS)
 - Better performances in flight safety compared to baseline performed at minima values (RVR reduced)

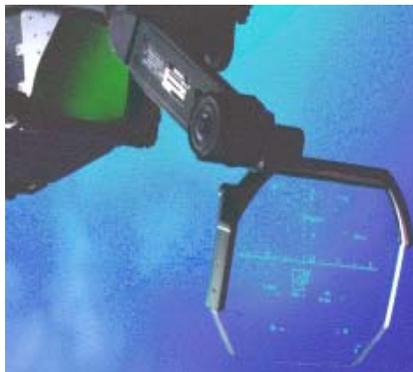


**EVS function in a HUD improves airfield approaches
for CAT I and NONP for large aircraft
under reduced visual conditions with fog**

- Is ready to work in partnership with customers to **save money** and **improve safety of flight** using HUDs fitted with EVS function.

THALES HUD-EVS LRUs for BOMBARDIER GEX

**Projector
and Combiner**



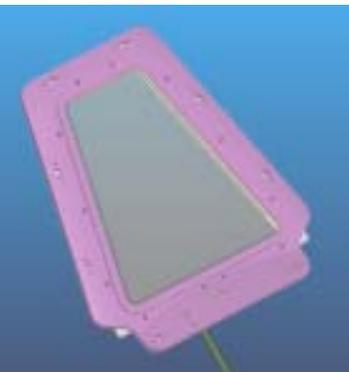
**Head-up
Flight Display
Computer**



**InfraRed
Sensor
Unit (ISU)**



**InfraRed
Window (IRW)**



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CMC